AN INVESTIGATION INTO THE STRUCTURE OF DIGROUPS

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ABSTRACT. In this paper we investigate the algebraic structure of digroups. We find a Lagrange-style correspondence between digroups and subdigroups. We also show how to construct a digroup containing any given number of identities whose order is any multiple of that number. Then, all digroups with inverse sets of prime order are classified. Additionally, the terms subdigroup, commutant, trivial digroup, idempotency class, are defined with basic results proven with regard to each term. Finally, various structural propositions are proven which may be useful in future digroup research.

1. INTRODUCTION

Since 2004, the notion of a digroup has been considered by Felipe [3], Kinyon [4], Phillips [12], Crompton and Scalici [2], and Liu [6]. Digroups were introduced to provide a partial solution to the Coquecigrue problem of generalizing Lie's Third Theorem for Leibniz Algebras, originally proposed in [7]. Kinyon's [4] definition of a digroup is as follows:

Definition 1.1. A digroup is a set G with two binary operations, \vdash and \dashv , a unary operation $^{-1}$ and a nullary operation 1, which satisfies:

G1. (G, \vdash) and (G, \dashv) are both semigroups G2. $(x \vdash y) \dashv z = x \vdash (y \dashv z)$ G3. $x \dashv (y \vdash z) = x \dashv (y \dashv z)$ G4. $(x \dashv y) \vdash z = (x \vdash y) \vdash z$ G5. $1 \vdash x = x = x \dashv 1$ G6. $x \vdash x^{-1} = 1 = x^{-1} \dashv x$

Phillips [12] proved that G_2, G_3 , and G_4 could be replaced with G_2^* :

 $G2^*.x \vdash (x \dashv z) = (x \vdash x) \dashv z$

The axiomatization was then shown to be equivalent to the following by Crompton and Scalici [2]:

 $G1^*$ (G, \vdash) and (G, \dashv) are both **semi-Moufang**, or $x \vdash ((y \vdash z) \vdash x) = (x \vdash y) \vdash (z \vdash x)$ and

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$$\begin{aligned} x \dashv ((y \dashv z) \dashv x) &= (x \dashv y) \dashv (z \dashv x) \\ G2. \ (x \vdash y) \dashv z &= x \vdash (y \dashv z) \\ G5. \ 1 \vdash x &= x = x \dashv 1 \\ G6. \ x \vdash x^{-1} &= 1 = x^{-1} \dashv x \end{aligned}$$

It is possible that this axiomatization can still be simplified. For instance, Phillips [12] did not use G1 to prove G2 from $G2^*$, G5, and G6. Thus, Crompton could have replaced G2 by $G2^*$ and still have derived G1 from $G1^*$, making the axiomatization $G1^*$, $G2^*$, G5, G6 equivalent to Kinyon's [4]. The software program PROVER9 [9] was used to prove that the following two relations are equivalent to semi-Moufang in the axiomatization of digroups:

Semi-Extra:	$x \vdash (y \vdash (z \vdash x)) = ((x \vdash y) \vdash z) \vdash x$ and
	$x \dashv (y \dashv (z \dashv x)) = ((x \dashv y) \dashv z) \dashv x$
Semi-Bol:	$x \vdash ((y \vdash z) \vdash x) = (x \vdash y) \vdash (z \vdash x),$
	$x \dashv ((y \dashv z) \dashv x) = (x \dashv y) \dashv (z \dashv x),$
	$((z \vdash x) \vdash y) \vdash x = z \vdash ((x \vdash y) \vdash x)$, and
	$((z \dashv x) \dashv y) \dashv x = z \dashv ((x \dashv y) \dashv x)$

However, replacing G1 with either of these would be even more unwieldly, and we only present them as an example of other directions to go with the axiomatization. For our purposes in this paper, we shall use Phillips' definition. Namely,

Definition 1.2. A digroup is a set G with two binary operations, \vdash and \dashv , a unary operation $^{-1}$ and a nullary operation 1, which satisfies: G1. (G, \vdash) and (G, \dashv) are both semigroups $G2^* x \vdash (x \dashv z) = (x \vdash x) \dashv z$ G5. $1 \vdash x = x = x \dashv 1$ G6. $x \vdash x^{-1} = 1 = x^{-1} \dashv x$

In the digroup, 1 is called a **bar unit** and x^{-1} is the **inverse** of x with respect to 1. It must be noted that a digroup can have multiple elements that act as bar units, but must always have at least one. An **identity** is an element $e \in G$ such that $e \vdash x = x = x \dashv e$ and $x \vdash x_{\vdash}^{-1} = e = x_{\dashv}^{-1} \dashv x$ for all $x \in G$ but x_{\vdash}^{-1} is not necessarily equal to x_{\dashv}^{-1} . If they are equal for all $x \in G$, e is a bar unit. We shall call x_{\vdash}^{-1} the **right inverse** of x and x_{\dashv}^{-1} the **left inverse** of x.

It should be noted that Liu [6] uses a slightly different definition of digroup, in which none of the identities is necessarily a bar unit. Liu's G6 is as follows:

 $G6_L$: for all $x \in G$, there exists x_{\vdash}^{-1} , $x_{\dashv}^{-1} \in G$ such that $x_{\dashv}^{-1} \dashv x = 1 = x \vdash x_{\vdash}^{-1}$.

For an example of a Cayley table that is a digroup under Lius definition, but not for Definition 1.2, see http://persweb.wabash.edu/facstaff/phillipj/research.html.

Next we define a **trivial digroup** as one which is composed entirely of identities:

\vdash	0	1	2	 n		\neg	0	1	2	 n
0	0	1	2	 n	-	0	0	0	0	 0
1	0	1	2	 n		1	1	1	1	 1
2	0	1	2	 n		2	2	2	2	 2
n	0	1	2	 n		n	n	n	n	 n

We note that there is one such digroup of each order $n \in \mathbb{N}$, and that every element of a trivial digroup acts as a bar unit.

The next lemma requires a definition of right and left group. Given a semigroup (G, \vdash) , we say (G, \vdash) is a **right group** if G contains a left identity $e \in G$ and a right inverse x^{-1} for each $x \in G$. Left group is defined in a similar fashion. If (G, \vdash, \dashv) forms a digroup, then (G, \vdash) forms a right group and (G, \dashv) forms a left group.

Lemma 1.3. Let (G, \vdash) be a right group. We define the set of identities $E = \{e \in G | e \vdash x = x \text{ for all } x \in G\}$ and the set of inverses $J = \{x^{-1} | x \in G\}$ with respect to any bar unit. It has been proven (e.g. [4]) that

- (1) J is a group
- (2) $G = J \vdash E \cong (J \times E, \vdash)$
- (3) A digroup is a group $\Leftrightarrow \vdash = \dashv \Leftrightarrow$ the bar unit is the only identity.
- (4) $x \vdash 1 = (x^{-1})^{-1}$ for all $x \in G$
- (5) $((x^{-1})^{-1})^{-1} = x^{-1}$ for all $x \in G$
- (6) $(x \vdash y)^{-1} = y^{-1} \vdash x^{-1}$ for all $x, y \in G$
- (7) $x \vdash 1 = x$ if and only if G is a group.

Corollary 1.4. $|G| = |J| \cdot |E|$

Proof. Follows directly from (2).

Corollary 1.5. Let G be a digroup. If |G| = p where p prime, then G is either the cyclic group \mathbb{Z}_p or a trivial digroup.

Proof. By 1.4 $|E| \mid |G|$. Since |G| is prime |E| = |G| or |E| = 1. If |E| = 1 we know from 1.3 that G is a group. Since |G| is prime, this means that G is a cyclic group. If |E| = |G|, then G is the trivial digroup of order |G| by definition.

In Section 3, statements corresponding to (1),(4),(5),(6), and (7) are proven to hold with respect to any identity in G.

Definition 1.6. We call a subset H of a digroup G a **subdigroup** if H has the structure of a digroup under the operations of G.

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This definition varies slightly from the one given in [3] in that it removes the condition that the bar unit of H must be the same bar unit in G. Thus, Felipe's subdigroup test needs to be modified appropriately:

Theorem 1.7. *H* is a subdigroup of *G* if and only if *H* contains a bar unit *e*, and for all *f*, *g*, *l*, *m*, $n \in H$ the elements $f \vdash e$, $g^{-1} \vdash l$, and $m \dashv n^{-1}$ are in *H*.

Proof. By adding the condition that H must contain a bar unit, the proof follows from Theorem 3.3 found in [3].

Felipe's definition of subdigroups and his test for subdigroups are such that everything Felipe proves to be a subdigroup is also a subdigroup under definition 1.6. We will, however, use Felipes definition of normal subdigroup (assuming subdigroup is defined according to definition 1.6):

Definition 1.8. A subdigroup, H of digroup G is called a **normal subdigroup** if and only if $a^{-1} \vdash x \dashv a \in H$ for all $a \in G$ and any $x \in H$.

2. Commutant

In [3], Felipe defined the commutant, or center, of a digroup as $Z(G) = \{x \in G | g \vdash x = x \dashv g \text{ for all } g \in G\}$ and proved it was a subdigroup. However, there are other possible definitions for a commutant that can be considered:

 $C1 = \{x \in G | g \vdash x = x \vdash g \text{ for all } g \in G\}$ $C2 = \{x \in G | g \dashv x = x \dashv g \text{ for all } g \in G\}$ $C3 = \{x \in G | g \dashv x = x \vdash g \text{ for all } g \in G\}$ $C4 = \{x \in G | g \vdash x = x \dashv g \text{ for all } g \in G\} = Z(G)$

Problem 2.1. It is still open to define the **centralizer** of an element in a digroup and prove it is a subdigroup.

C1 and C2 are only subdigroups when G is a group because $1 \in C1$ if and only if $1 \vdash x = x \vdash 1 = x$, thus by Lemma 1.3 (7), G must be a group. A similar argument can be made for C2. Also, any union or intersection of C1 and C2 is insufficient as they only form subdigroups when G is a group. Thus, C1 and C2 do not represent proper generalizations of the center of a group as they do not necessarily form subdigroups of G.

Thus, we are left to consider C3. Using PROVER9 [9], it was proven that:

Proposition 2.2. C3 is a normal subdigroup of digroup G, where 1 is a bar unit of G. We must show that:

- (1) C3 contains a bar unit.
- (2) $x \in C3 \Rightarrow x^{-1} \in C3.$

- (3) $x \in C3 \Rightarrow x \vdash 1 \in C3.$
- (4) $x, y \in C3 \Rightarrow x^{-1} \vdash y \in C3.$
- (5) $x, y \in C3 \Rightarrow x \dashv y^{-1} \in C3.$
- (6) $x \in C3 \Rightarrow ((g^{-1} \vdash x) \dashv g) \in C3$ for all $g \in G$.

Proof. In this proof we shall also make use of the fact that if 1 is a bar unit, then $1 \in C4$; proven in [3]. Let $x \in C3$.

- (1) $1 \vdash x = x = x \dashv 1 \Rightarrow 1 \in C3.$
- (2) Since $x \in C3$, $x \vdash y = y \dashv x$ for all $y \in G \Rightarrow x \vdash (a \dashv b) \stackrel{(C3)}{=} (a \dashv b) \dashv x \stackrel{(G1)}{=} a \dashv (b \dashv x) \stackrel{(C3)}{=} a \dashv (x \vdash b)$ for all $a, b \in G$. If we let $b = x^{-1}$, this equation becomes $a = x \vdash (a \dashv x^{-1})$.

We know from Lemma 1.3 that $(c^{-1})^{-1} = c \vdash 1 \Rightarrow c^{-1} \vdash (c \vdash 1) = 1$ by the definition of inverse. Therefore $c^{-1} \vdash ((c \vdash 1) \vdash d) \stackrel{(G1)}{=} (c^{-1} \vdash (c \vdash 1)) \vdash d = 1 \vdash d = d$ for all $c, d \in G$.

Since $a = x \vdash (a \dashv x^{-1})$, $x^{-1} \vdash a = x^{-1} \vdash (x \vdash (a \dashv x^{-1})) = a \dashv x^{-1}$ by the above equation with c = x and $d = a \dashv x^{-1}$. This proves $x^{-1} \in C3$.

- (3) Since $x \in C3$, $(x \vdash 1) \vdash g \stackrel{(G1)}{=} x \vdash (1 \vdash g) = x \vdash g \stackrel{(C3)}{=} g \dashv x = (g \dashv 1) \dashv x \stackrel{(G1)}{=} g \dashv (1 \dashv x) \stackrel{(C3)}{=} g \dashv (x \vdash 1)$. Therefore, $x \vdash 1 \in C3$.
- (4) Let $A, B \in C3$. Then $A \vdash x = x \dashv A$ and $B \vdash x = x \dashv B$ for all $x \in G$. Note that by (2) above, $A^{-1} \vdash x = x \dashv A^{-1}$ and $B^{-1} \vdash x = x \dashv B^{-1}$ for all $x \in G$.

$$(A^{-1} \vdash B) \vdash x \stackrel{(G1)}{=} A^{-1} \vdash (B \vdash x) \stackrel{(C3)}{=} (B \vdash x) \dashv A^{-1} \stackrel{(C3)}{=} (x \dashv B) \dashv A^{-1} \stackrel{(G1)}{=} x \dashv (B \dashv A^{-1}) \stackrel{(C3)}{=} x \dashv (A^{-1} \vdash B) \text{ which proves } (A^{-1} \vdash B) \in C3.$$

(5) $A, B \in C3 \Rightarrow A \vdash x = x \dashv A$ and $B \vdash x = x \dashv B$ for all $x \in G$.

$$(A \dashv B^{-1}) \vdash x \stackrel{(G4)}{=} A \vdash B^{-1} \vdash x \stackrel{(C3)}{=} A \vdash (x \dashv B^{-1}) \stackrel{(G2)}{=} (A \vdash x) \dashv B^{-1} \stackrel{(C3)}{=} (x \dashv A) \dashv B^{-1} \stackrel{(G1)}{=} x \dashv (A \dashv B^{-1}) \text{ proving } A \dashv B^{-1} \in C3.$$

(6) $A \in C3 \Rightarrow A \vdash x = x \dashv A.$

Suppose not, i.e. $b \dashv ((a^{-1} \vdash A) \dashv a) \neq ((a^{-1} \vdash A) \dashv a) \vdash b$. Note that $\underbrace{((a^{-1} \vdash A) \dashv a) \vdash b}_{a^{-1}} \stackrel{(G4)}{=} (a^{-1} \vdash A) \vdash (a \vdash b) \stackrel{(G1)}{=} a^{-1} \vdash (A \vdash (a \vdash b)) \stackrel{(C3)}{=} a^{-1} \vdash ((a \vdash b) \dashv A) \stackrel{(G2)}{=} (a^{-1} \vdash (a \vdash b)) \dashv A \stackrel{(C3)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G1)}{=} (A \vdash a^{-1}) \vdash (a \vdash b) \stackrel{(G1)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G1)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G1)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G2)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G3)}{=} A \vdash (a^{-1} \vdash (a \vdash b)) \stackrel{(G4)}{=} A \vdash (a^{-1} \vdash (a^{-1} \vdash b)) \stackrel{(G4)}{=} A \vdash (a^{-1} \vdash b)$ $b))) \stackrel{(G1)}{=} A \vdash ((a^{-1} \vdash (a \vdash 1)) \vdash b) = A \vdash (1 \vdash b) \stackrel{(G5)}{=} \underline{A \vdash b}$ by Lemma 1.3 and $\underline{b} \dashv ((a^{-1} \vdash A) \dashv a) \stackrel{(G2)}{=} b \dashv ((a^{-1} \vdash A) \vdash a) \stackrel{(G1)}{=} b \dashv (a^{-1} \vdash (A \vdash a)) \stackrel{(G3)}{=} b$ $b \dashv a^{-1} \dashv (A \vdash a) \stackrel{(C3)}{=} b \dashv (a^{-1} \dashv (a \dashv A)) \stackrel{(G1)}{=} b \dashv ((a^{-1} \dashv a) \dashv A) \stackrel{(C3)}{=} b \dashv (A \vdash (a^{-1} \dashv a)) \stackrel{(G3)}{=} b \dashv (A \vdash (a^{-1} \dashv a)) \stackrel{(G3)}{=} b \dashv (A \vdash (a^{-1} \dashv a)) \stackrel{(G3)}{=} b \dashv (A \vdash (a^{-1} \dashv a)) \stackrel{(G4)}{=} b \dashv (a^{-1} \dashv a) \stackrel{(G3)}{=} A \vdash (b \dashv (a^{-1} \dashv a)) \stackrel{(G4)}{=} A \vdash (b \dashv (a^{-1} \vdash a))) \stackrel{(G4)}{=} A \vdash (b \dashv (a^{-1} \vdash a)) \stackrel{(G4)}{=} A \vdash (b \dashv (a^{-1} \vdash a))) \stackrel{(G4)}{=} A \vdash (b \dashv (a^{-1} \dashv a)) \stackrel{(G4)}{=} A \vdash (a^{-1} \dashv a) \vdash a) \stackrel{(G4)}{=} a^{-1} \dashv a) \stackrel{(G4)}{=} a^{-1$

Therefore,
$$((a^{-1} \vdash A) \dashv a) \vdash b = b \dashv ((a^{-1} \vdash A) \dashv a).$$

Since C3 and C4 are normal subdigroups and are non-equivalent (for a digroup in which $C3 \neq C4$, see $D_2(6, \mathbb{Z}_2)$ in Section 6), both are candidates for the commutant of a digroup.

Felipe [3] defines an **abelian digroup** G as one in which $x \dashv y = y \vdash x$ for all $x, y \in G$. Note that in any abelian digroup G, C3 = C4 = G. Also, $E \subseteq C3$.

Many open problems still exist with regard to this aspect of digroups, and some are listed below.

Problem 2.3. Find a correspondence for the **class equation** from group theory.

Problem 2.4. Define Nilpotency for digroups by taking the quotient structure of a digroup with C3 or C4 using the method from [3].

Problem 2.5. Do a comparative analysis of the two commutant definitions and find out which is better. Or, alternately, find a new definition based on C3 and C4 that encapsulates the best qualities of both.

3. Subdigroups

In previous literature (e.g. [3], [4]), the set of inverses, J, was specifically the set of inverses with respect to the defined bar unit, 1. The following results rely upon the set of inverses with respect to any identity, e. We define $J_e^{\vdash} = \{h_{\vdash}^{-1} | h \vdash h_{\vdash}^{-1} = e\}$, where $h \in G$, $e \in E$, and G is a digroup. The notation, h_{\vdash}^{-1} denotes the inverse of h under \vdash with respect to e. We will use similar notation for \dashv . It is important to note that the identity h_{\vdash}^{-1} is taken with respect to is not specified in the notation, but should be clear in the given context. Also, h_{\vdash}^{-1} does not necessarily equal h_{\dashv}^{-1} , or in other words, an element of a digroup can have a different inverse under each operation with respect to the same identity. However, if the identity is also a bar unit, then $h_{\vdash}^{-1} = h_{\dashv}^{-1}$ and $J_e^{\vdash} = J_e^{\dashv}$. The following Lemma shows that many of the results of Lemma 1.3 hold with respect to any arbitrary identity.

Lemma 3.1. Let (G, \vdash) be a right group. Let J_e^{\vdash} be defined as above with $e \in E$. Let $x, y \in G$. Assume all inverses are with respect to e.

(1) for every $x \in G$, there exists an x_{\vdash}^{-1}

- (2) $x \vdash e = (x_{\vdash}^{-1})_{\vdash}^{-1}$
- (3) $(x \vdash y)_{\vdash}^{-1} = y_{\vdash}^{-1} \vdash x_{\vdash}^{-1}$
- $(4) \ ((x_{\vdash}^{-1})_{\vdash}^{-1})_{\vdash}^{-1} = x_{\vdash}^{-1}$
- (5) $x \vdash e = x$ if and only if G is a group
- (6) $J_e^{\vdash} = J \vdash e = \{a \vdash e \mid a \in J\}$
- (7) $J_e^{\vdash} \cong J$, as groups under \vdash
- (8) The sets J_e^{\vdash} for all $e \in E$ partition G
- *Proof.* (1) Since $G = J \vdash E$, let $x = a \vdash e'$, for some $a \in J$ and $e' \in E$. Then, $(a \vdash e') \vdash (a^{-1} \vdash e) = a \vdash (e' \vdash a^{-1}) \vdash e = (a \vdash a^{-1}) \vdash e = 1 \vdash e = e$. Therefore, $a^{-1} \vdash e = x_{\vdash}^{-1}$.

(2)
$$x \vdash e = x \vdash (x_{\vdash}^{-1} \vdash (x_{\vdash}^{-1})_{\vdash}^{-1}) = e \vdash (x_{\vdash}^{-1})_{\vdash}^{-1} = (x_{\vdash}^{-1})_{\vdash}^{-1}.$$

- (3) Note that $(x \vdash y) \vdash y_{\vdash}^{-1} \vdash x_{\vdash}^{-1} = e$, thus $y_{\vdash}^{-1} \vdash x_{\vdash}^{-1} = (x \vdash y)_{\vdash}^{-1}$.
- (4) $((x_{\vdash}^{-1})_{\vdash}^{-1})_{\vdash}^{-1} = (x \vdash e)_{\vdash}^{-1} = e \vdash x_{\vdash}^{-1} = x_{\vdash}^{-1}$, by (1) and (2).
- (5) (\Rightarrow) Assume $e_1 \in G$, and let $x = e_1$, then $e_1 = e$. Therefore, e is the only identity in G, thus e must be a bar unit, and then by Lemma 1.3 (3), G is a group. (\Leftarrow) Trivial.
- (6) Let $a \vdash e \in J \vdash e$. Since $a \in J$, and J is a group under \vdash , there exists a $b \in J$ such that $b \vdash a = 1$. Thus, $b \vdash (a \vdash e) = (b \vdash a) \vdash e = 1 \vdash e = e$. This means that $a \vdash e = b_{\vdash}^{-1} \in J_e^{\vdash}$. Now, let $x \in J_e^{-1}$. Thus, there exists a $y \in G$ such that $y \vdash x = e$. Since $G = J \vdash E$, $y = a' \vdash e'$ and $x = a'' \vdash e''$, for some $a', a'' \in J$ and $e', e'' \in E$. So, $e = y \vdash x = (a' \vdash e') \vdash (a'' \vdash e'') = a' \vdash (e' \vdash a'') \vdash e'' = (a' \vdash a'') \vdash e''$. Since $e = 1 \vdash e$, $a' \vdash a'' = 1$ and e'' = e. Thus, $x = a'' \vdash e \in J \vdash e$.
- (7) Consider $\phi: J_e^{\vdash} \to J$ defined by $\phi(a \vdash e) = a$, for every $a \in J$. Clearly, ϕ is bijective. To show that ϕ is a group homomorphism, consider $\phi((a_1 \vdash e) \vdash (a_2 \vdash e)) = \phi((a_1 \vdash a_2) \vdash e) = a_1 \vdash a_2 = \phi(a_1 \vdash e) \vdash \phi(a_2 \vdash e)$.

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(8) This follows from the observation that $G = J \vdash E$ is partitioned into $J \vdash e = J_e^{\vdash}$, for all $e \in E$.

Lemma 3.2. Let (G, \vdash, \dashv) be a digroup, then $g \vdash J_e^{\vdash} = J_e^{\vdash}$ for all $g \in G$ and for all $e \in E$.

Proof. (⊆) Take $a \in J$ and $g = a' \vdash e' \in G$. Then, $g \vdash (a \vdash e) = (a' \vdash a) \vdash e \in J \vdash e$. (⊇) Take $a \vdash e \in J \vdash e$ and $g = a' \vdash e' \in G$. Then, $g \vdash (((a')^{-1} \vdash a) \vdash e) = (a' \vdash ((a')^{-1} \vdash a)) \vdash e = 1 \vdash (a \vdash e) = a \vdash e$.

This result also holds for the corresponding \dashv statement: $J_{\dashv}^{-1} \dashv g = J_{\dashv}^{-1}$.

Lemma 3.3. Given a digroup G, all nonempty subsets of E form a subdigroup.

Proof. A subset of G composed entirely of identities forms a trivial subdigroup in which all elements act as bar units. \Box

Theorem 3.4. Let (G, \vdash, \dashv) be a digroup. Consider any nonempty subset S of E such that $S = \{e_1, e_2, ..., e_n\}$, and there exists an $e_j \in S$ that is a bar unit. Let $H = J_{e_1}^{\vdash} \cup J_{e_2}^{\vdash} \cup ... \cup J_{e_n}^{\vdash}$, then H forms a subdigroup of G if $J_{e_1}^{\vdash} \cup J_{e_2}^{\vdash} \cup ... \cup J_{e_n}^{\vdash} = J_{e_1}^{\dashv} \cup J_{e_2}^{\dashv} \cup ... \cup J_{e_n}^{\dashv}$.

Proof. According to Theorem 1.7, we must show there exists a bar unit $e \in H$ and that for all $f, g, l, m, n \in H$, the elements $f \vdash e, g^{-1} \vdash l$, and $m \dashv n^{-1}$ are contained in H. Clearly, $e_j \in H$. Now we must show that for each $x \in H, x^{-1}$ with respect to e_i is also in H. By Lemma 3.2, we know $x \vdash J_{e_i}^{\vdash} = J_{e_i}^{\vdash}$. Since $e_i \in J_{e_i}^{\vdash}$, then $x^{-1} \in J_{e_i}^{\vdash} \subseteq H$. Now we consider closure: $f \vdash e_i \in f \vdash J_{e_i}^{\vdash} = J_{e_i}^{\vdash}$; we know $l \in J_{e_k}^{\vdash}$ for some k such that $1 \leq k \leq n$, thus $g^{-1} \vdash l \in J_{e_k}^{\vdash} \subseteq H$; and similarly, we know $m \in J_{e_r}^{\dashv}$ for some r such that $1 \leq r \leq n$, thus $m \dashv n^{-1} \in J_{e_r}^{\dashv} \subseteq H$. Thus, H is a subdigroup of G.

Corollary 3.5. The subset, K, of G defined as $K = J_{e_1} \cup J_{e_2} \cup ... \cup J_{e_m}$ where $e_j \in S$ is a bar unit for all $j, 1 \leq j \leq m$, forms a subdigroup of G.

Proof. By definition of bar unit, $J_{e_j}^{\vdash} = J_{e_j}^{\dashv}$ for all t such that $1 \leq j \leq m$. Thus, K = H as defined in Theorem 3.4 for some S, making K a subdigroup of G.

According to Corollary 3.5, we can form $\sum_{j=1}^{m} \binom{m}{j}$ subdigroups of G where m is the number of bar units in G, simply by finding the union of the inverse sets with respect to any number of the bar units. However, Theorem 3.4 indicates that there are more subdigroups that can be formed from identities that are not necessarily bar units, provided they satisfy the additional property given to H. Additionally, by Lemma 3.2, $2^n - 1$ trivial subdigroups can be formed where n is the number of identities in G.

An observation that can be made from Theorem 3.4, is that the inverse sets determine, to a large extent, what subdigroups can be found in a given digroup. In sections 5 and 6, it is demonstrated that the structure of any given digroup can be understood by examining the structure of its set of inverses with respect to a bar

unit. This is helpful because the set of inverses with respect to a bar unit forms a group.

We now prove a generalization of Lagrange's Theorem.

Theorem 3.6. Let G be a digroup, and $H \subseteq G$ a subdigroup of G. Define J_H as the set of inverses in H with respect to a bar unit in H, and E_H and E_G as the set of identities in H and G, respectively. Let J_G be the set of inverses in G with respect to the same bar unit as J_H . If $|E_H| ||E_G|$ then |H| ||G|.

Proof. Since $J_H \subseteq J_G$, and J_H and J_G form groups, then by Lagrange's Theorem for groups, $|J_H| ||J_G|$. By Corollary 1.4, $|G| = |J_G| \cdot |E_G| = n \cdot m \cdot |J_H| \cdot |E_H| = n \cdot m \cdot |H|$, where $n, m \in \mathbb{N}$. Thus, |H| ||G|.

In the case that H is a group, then $|E_H| = 1$ by Lemma 1.3 (3), thus by Theorem 3.6, |H|||G|. This shows that Theorem 3.6 provides an appropriate generalization of Lagrange's Theorem for groups. It is not the case, however, that the order of any given subdigroup will necessarily divide the order of the parent digroup.

Problem 3.7. It is still open to find a correspondence for the **Cauchy Theorem** from group theory. The next step after this would be to consider correspondences for the **Sylow Theorems**.

4. Order and Idempotency

In [6], finding a generalization for the order of an element in a digroup is left as an open problem. We provide a definition here:

Definition 4.1. Let G be a digroup. If n is the **order** of an element $x \in G$, then n is the least possible number of times x occurs in the expansion $x \vdash x \vdash x \vdash ... \vdash x = x_{\vdash}^n = e$ for some $e \in E$.

If order is defined according to \dashv , this definition would be identical to 4.1. The problem with this definition is that the order of all elements will be bounded by $|J_G|$ for reasons that will become clear in Section ??, rather than ranging through the possible divisors of |G| as is the case in group theory. A generalization of order, which holds for *every* element is Idempotency:

Definition 4.2. The **Idempotency class** (*I*-class) of an element x is the natural number n such that $x^n = x_{\dashv}^n = x_{\vdash}^n = x$ and $x^i \neq x$ for all 1 < i < n. The *I*-class of any identity element is 2. Let o(x) be the order of x, and I(x) be the *I*-class of x.

Proposition 4.3. Let x be an arbitrary element in G where |G| = n.

(1) Every element on the diagonal is $1 \Rightarrow I(x) = 3$ for all $x \neq 1$.

- (2) $x_{\vdash}^k = 1 \Rightarrow x_{\dashv}^k = 1$ for all $k \le n$.
- (3) The maximum order of an element is n.
- (4) The maximum I-class of an element is n + 1.

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(5) $I(x) - 1 = o(x) \Leftrightarrow G$ is a finite group.

Proof. Let x be an arbitrary element in G where |G| = n.

- (1) If every element on the diagonal is 1, $x \vdash x = 1$ for all x which implies that $x \vdash x \vdash x = 1 \vdash x = x$, so that I(x) = 3 for all $x \neq 1$.
- (2) $a \vdash x^{n-1} = 1 \Leftrightarrow x^{n-1} \dashv x = 1.$
- (3) Suppose not. Then $x^2 \neq 1, x^3 \neq 1, ..., x^{n+1} \neq 1$. By the Pigeonhole Principle, $x^l = x^m$ for some l, m < n + 1, which implies a cycle exists in which none of the powers is 1. This implies that the order is infinite.
- (4) This is a corollary of (3)
- (5) (\Leftarrow) *G* is finite, so all elements have finite order, so $x^n = 1 \Rightarrow x^{n+1} = x$ trivially.

 $(\Rightarrow) x^{n+1} = x$ and $x^n = 1$, so we know that $x^{n+1} \vdash x^{-1} = x \vdash x^{-1} = 1 = x^n = x^n \vdash 1$. Therefore, since \vdash is associative, $x \vdash 1 = 1$, which tells us G is a group by Remark 3.2 from [3].

In group theory, the order of an element $x \in G$ divides |G|. The following theorem is the generalization of this concept to digroups with Idempotency.

Theorem 4.4. For any element x of digroup G, I(x) - 1 ||G|.

The proof of this theorem is delayed until the concepts it relies on are introduced in Section 5.

Problem 4.5. With this concept of order, the next step is to consider the structure of cyclic digroups and theorems related to them.

Problem 4.6. It is also still open to define orbits and stabilizers in digroups and prove a correspondence of the **Orbit-Stabilizer Theorem**.

5. Classification of (G,\vdash)

Theorem 5.1. For any group H of order n, and for any $m \in \mathbb{N}$ there exists a digroup G such that the order of G is $m \cdot n$ and the inverse set J of G is isomorphic to H.

Proof. Let $H = \{1, 2, ..., n\}$, with binary operation \circ and identity 1. Let $E = \{1 = e_1, e_2, ..., e_m\}$. Let $G = H \times E$. Clearly, G has $m \cdot n$ elements. Let $\vdash: G \times G \to G$ be defined by $(i_1, e_{j_1}) \vdash (i_2, e_{j_2}) = (i_1 \circ i_2, e_{j_2})$. Let $\dashv: G \times G \to G$ be defined by $(i_1, e_{j_1}) \dashv (i_2, e_{j_2}) = (i_1 \circ i_2, e_{j_1})$. First, we will show that G satisfies the four digroup axioms.

(1) Every element has an inverse with respect to $(1, e_1)$: $(i, e_j) \vdash (i^{-1}, e_1) = (i \circ i^{-1}, e_1) = (1, e_1) = (i^{-1} \circ i, e_1) = (i^{-1}, e_1) \dashv (i, e_j)$ (2) $(1, e_1)$ is a bar unit:

$$(1, e_1) \vdash (i, e_j) = (1 \circ i, e_j) = (i, e_j) = (i \circ 1, e_j) = (i, e_j) \dashv (1, e_1)$$

(3) Associativity:

$$\begin{split} & [(i_1, e_{j_1}) \vdash (i_2, e_{j_2})] \vdash (i_3, e_{j_3}) = (i_1 \circ i_2, e_{j_2}) \vdash (i_3, e_{j_3}) = ((i_1 \circ i_2) \circ i_3, e_{j_3}) = \\ & (i_1 \circ (i_2 \circ i_3), e_{j_3}) = (i_1, e_{j_1}) \vdash (i_2 \circ i_3, e_{j_3}) = (i_1, e_{j_1}) \vdash [(i_2, e_{j_2}) \vdash (i_3, e_{j_3})] \\ & [(i_1, e_{j_1}) \dashv (i_2, e_{j_2})] \dashv (i_3, e_{j_3}) = (i_1 \circ i_2, e_{j_1}) \dashv (i_3, e_{j_3}) = ((i_1 \circ i_2) \circ i_3, e_{j_1}) = \\ & (i_1 \circ (i_2 \circ i_3), e_{j_1}) = (i_1, e_{j_1}) \dashv (i_2 \circ i_3, e_{j_2}) = (i_1, e_{j_1}) \dashv [(i_2, e_{j_2}) \dashv (i_3, e_{j_3})] \end{split}$$

(4) Axiom $G2^*$:

$$\begin{bmatrix} (i_1, e_{j_1}) \vdash (i_1, e_{j_1}) \end{bmatrix} \dashv (i_2, e_{j_2}) = (i_1 \circ i_1, e_{j_1}) \dashv (i_2, e_{j_2}) = ((i_1 \circ i_1) \circ i_2, e_{j_1}) = (i_1 \circ (i_1 \circ i_2), e_{j_1}) = (i_1, e_{j_1}) \vdash (i_1 \circ i_2, e_{j_1}) = (i_1, e_{j_1}) \vdash [(i_1, e_{j_1}) \dashv (i_2, e_{j_2})]$$

Next, we will show that $J \cong H$.

Consider $\phi : J \to H$ defined by $\phi((i, e_1)) = i$. Clearly, ϕ is bijective. To show that ϕ preserves the groups' operations:

$$\phi((i_1, e_1) \vdash (i_2, e_1)) = \phi((i_1 \circ i_2, e_1)) = i_1 \circ i_2 = \phi((i_1, e_1)) \circ \phi((i_2, e_1))$$

Definition 5.2. Two digroups G, with operations \vdash and \dashv , and G', with operations \vdash' and \dashv' , are (digroup) isomorphic if there exists a bijective function $f : G \to G'$ that preserves the operations of G; that is, $f(x \vdash y) = f(x) \vdash' f(y)$ and $f(x \dashv y) = f(x) \dashv' f(y)$, for all $x, y \in G$. If only the first of these holds, G and G' are said to be \vdash -isomorphic, and similarly for \dashv -isomorphisms.

Theorem 5.3. Two digroups (G, \vdash, \dashv) and (G', \vdash', \dashv') with non-isomorphic inverse sets must be non-isomorphic.

Proof. Assume $G \cong G'$. Let 1 be the bar unit of G. Let ϕ be a digroup isomorphism from G onto G'. For any $x \in G$, $1 \vdash x = x = x \dashv 1$ and $\phi(1 \vdash x) = \phi(x) = \phi(x \dashv 1)$. So, $\phi(1) \vdash \phi(x) = \phi(x) = \phi(x) \dashv \phi(1)$. Similarly, $\phi(x \vdash x^{-1}) = \phi(1) = \phi(x^{-1} \dashv x)$ and $\phi(x) \vdash \phi(x^{-1}) = \phi(1) = \phi(x^{-1}) \dashv \phi(x)$. Thus, $\phi(1)$ is the bar unit of G'. Let Jand J' be the inverse sets of G and G', respectively. Now, we will show that ϕ restricted to J is a group isomorphism between J and J'. Let $a \in J$. Then, there exists an $b \in G$ such that $b \vdash a = 1$. So, $\phi(b) \vdash' \phi(a) = \phi(1)$. Thus, $\phi(a) \in J'$. Similarly, if $\phi(a) \in J'$, then $a \in J$. This shows that ϕ restricted to J maps into J' and is bijective (since ϕ itself is injective). Since ϕ preserves the operation \vdash of G, which is the group operation of J, it also preserves that operation for J. Therefore, $J \cong J'$.

Theorem 5.4. Two digroups of the same order with isomorphic inverse sets must $be \vdash -isomorphic$.

Proof. Let (G, \vdash, \dashv) and (G', \vdash', \dashv') be digroups of the same order whose inverse sets J and J', respectively, are isomorphic. Let $\phi : J \to J'$ be an isomorphism. Let $E = \{e_1, e_2, ..., e_n\}$ and $E' = \{e_1', e_2', ..., e_n'\}$ be the sets of identities of Gand G', respectively, with e_1 and e_1' as the bar units of those respective digroups. Note that since the digoups have the same order and their inverse sets also have the same order (since they are isomorphic), the sets of identities must have the same order, which we assumed is n. Now, consider the function $\Phi : G \to G'$ defined by $\Phi(a_j \vdash e_i) = \phi(a_j) \vdash' e_i'$, where the elements of J are enumerated $a_1, a_2,$..., a_m . Clearly, Φ is bijective. To show that Φ preserves the operation \vdash for G, consider $\Phi((a_{j_1} \vdash e_{i_1}) \vdash (a_{j_2} \vdash e_{i_2})) = \Phi((a_{j_1} \vdash a_{j_2}) \vdash e_{i_2}) = \phi(a_{j_1} \vdash a_{j_2}) \vdash' e_{i_2'} =$ $(\phi(a_{j_1}) \vdash' e_{i_1'}) \vdash' (\phi(a_{j_2}) \vdash' e_{i_2'}) = \Phi(a_{j_1} \vdash e_{i_1}) \vdash' \Phi(a_{j_2} \vdash e_{i_2})$. Therefore, G and G' are \vdash -isomorphic.

Theorem 5.5. The number of distinct \vdash -structures of digroups of order n is $\Sigma_{i=I}g(m_i)$, where the m_i are the factors of n, and g(m) is the number of groups of order m.

Proof. Consider all digroups of order n. It is known that all of those digroups' inverse sets must be groups of orders that divide n. From Theorem 5.1, we know that all such groups can be realized as the inverse set of some digroup of order n. Then, from Theorem 5.3, we know that there are at least $\sum_{i=I} g(m_i)$ distinct digroups of order n, corresponding to each possible group that could be an inverse set. Finally, Theorem 5.4 insures this lower bound on the number of digroups of order n is actually an equality, when considering the distinct \vdash -structures. \Box

Of course, the question still remains of how many digroups of order n there are. It is known how many distinct \vdash -structures there can be of such digroups, but there are examples of digroups that are \vdash -isomorphic and \dashv -isomorphic, but not digroup isomorphic. In the next section, we examine this issue in further detail, and obtain some preliminary results.

Now, consider any digroup G of order mn that has $J = \{a_1, a_2, ..., a_n\}$ as its inverse set and $E = \{e_1, ..., e_m\}$ has its set of identities. Rearrange the rows and columns of the Cayley table of \vdash for G in such a way that the first row and the first column (that is, the row and column that list the multiplicands) are in the following order: $a_1 \vdash e_1, a_2 \vdash e_1, ..., a_n \vdash e_1, a_1 \vdash e_2, a_2 \vdash e_2, ..., a_n \vdash e_2, ..., a_1 \vdash e_m, a_2 \vdash e_m, ..., a_n \vdash e_m$. (see the following table).

F	$a_1 \vdash e_1 a_2 \vdash e_1 \cdots a_n \vdash e_1$	•••	$a_1 \vdash e_m a_2 \vdash e_m \cdots a_n \vdash e_m$
$a_1 \vdash e_1$			
$a_2 \vdash e_1$			
:	$(J \vdash J) \vdash e_1$		$(J \vdash J) \vdash e_m$
$a_n \vdash e_1$			
÷			
$a_1 \vdash e_m$			
$a_2 \vdash e_m$			
:	$(J \vdash J) \vdash e_1$		$(J \vdash J) \vdash e_m$
$a_n \vdash e_m$			

The columns are grouped according to their inverse sets and the first n rows are all distinct, with the next n rows repeating the first, in exact order, and so on, until the last n rows, which are the first n repeated in exact order. Thus, once the first n rows are determined, the entire Cayley table will be determined by just rewriting the first n rows m-1 more times. The first n rows and columns correspond to J (since they form the inverse set of e_1 , which is the actual inverse set of G). Thus, the top-left $n \times n$ square of the Cayley table is just the Cayley table for J. Since $(a_{i_1} \vdash e_1) \vdash (a_{i_2} \vdash e_j) = (a_{i_1} \vdash a_{i_2}) \vdash e_j$, the next $n \times n$ square (since we are now only considering the first n rows) is just $(J \vdash J) \vdash e_2$, and so on, until the last $n \times n$ square is just $(J \vdash J) \vdash e_m$, where $(J \vdash J) \vdash e_i$ means that the element in the k_1 -th row and k_2 -th column of $(J \vdash J) \vdash e_i$ is $(a_{k_1} \vdash a_{k_2}) \vdash e_i$. This means that since the first row is just the identity row, however the elements of Jare permuted in each new row is exactly how the elements of every $n \times n$ square will be permuted. Thus, from J alone, the entire Cayley table is determined up to isomorphism. This construction is the main idea behind the proof of Theorem 5.4. As noted above, while a similar construction can be done with the \dashv Cayley table of a digroup of order mn, so that two such digroups with J as their inverse sets will be both \vdash -isomorphic and \dashv -isomorphic, there is no guarantee that the digroups will be digroup isomorphic. This problem arises because the partitioning of the digroups into $J \vdash E$ and $E \dashv J$ may not yield the same partitions since the identities are not necessarily bar units.

As an example of the above construction, consider the following \vdash Cayley table of a digroup of order 6 :

\vdash	0	1	2	3	4	5
0	1	0	3	2	5	4
1	0	1	2	3	4	5
2	1	0	3	2	5	4
3	0	1	2	3	4	5
4	1	0	3	2	5	4
5	0	1	2	3	4	5

Now consider the Cayley tables of the partitions $\{0, 1\}, \{2, 3\}, \{4, 5\}$:

\vdash	0	1	\vdash	2	3	\vdash	4	5
0	1	0	2	3	2	4	5	4
1	0	1	3	2	3	5	4	5

Notice how these tables correspond to \mathbb{Z}_2 . Every digroup generated using MACE4 has a \vdash -structure that can be arranged in this form. The digroup whose \dashv Cayley table can be arranged in the same way with the same partitions we call the **Principal Digroup**. The above example with the same \dashv Cayley table would be called the principal digroup of order 6 based upon \mathbb{Z}_2 . The notation $D_i(n, J)$ can be used to represent digroups where i = 1 corresponds to the principal digroup, $n = |\mathbf{G}|$, and J corresponds to the basis group, or the set of inverses. The above example would be represented $D_1(6,\mathbb{Z}_2)$. The following table generated by MACE4 [9] shows this classification for all the digroups up to order 15. The ISOFILTER function ensured that only non-isomorphic structures were considered.

Note that with this notion of digroups based upon groups we can prove Theorem 4.4:

Proof. We know

- (1) $I(x) 1 = o(x) \Leftrightarrow H$ is a finite group from (5) above.
- (2) o(x) |H| for all $x \in H$.
- (3) |H|||G|.
- From these, we can see that $o(x) | H \Rightarrow (I(x) 1) | H \Rightarrow (I(x) 1) | |G|.$

Table .	I: D	igroups up to order 15
Order	$ \mathbf{J} $	Name
2	2	\mathbb{Z}_2
	1	trivial
3	3	\mathbb{Z}_3
	1	trivial
4	4	$\mathbb{Z}_4, \mathbb{Z}_2 imes \mathbb{Z}_2$
	2	$\mathrm{D}_1(4,\mathbb{Z}_2)$
	1	trivial
5	5	\mathbb{Z}_5
	1	trivial
6	6	$\mathbb{Z}_6, \mathbb{D}_3$
	3	$\mathrm{D}_1(6,\mathbb{Z}_3)$
	2	$D_1(6, \mathbb{Z}_2), D_2(6, \mathbb{Z}_2)$
	1	trivial
7	7	\mathbb{Z}_7
	1	trivial
8	8	$\mathbb{Z}_8, \mathbb{Z}_4 \times \mathbb{Z}_2, \mathbb{Z}_2 \times \mathbb{Z}_2 \times \mathbb{Z}_2, \mathrm{D}_4, \mathrm{Q}$
	4	$D_1(8, \mathbb{Z}_4), D_1(8, \mathbb{Z}_2 \times \mathbb{Z}_2)$
	2	$D_1(8, \mathbb{Z}_2), D_2(8, \mathbb{Z}_2)$
	1	
9	9	$\mathbb{Z}_9, \mathbb{Z}_3 imes \mathbb{Z}_3$
	3	$D_1(9, \mathbb{Z}_3)$
	1	trivial
10	10	$\mathbb{Z}_{10}, \mathbb{D}_5$
	5	$D_1(10, \mathbb{Z}_5)$
	2	$D_1(10, \mathbb{Z}_2), D_2(10, \mathbb{Z}_2), D_3(10, \mathbb{Z}_2)$
	1	trivial
11	11	\mathbb{Z}_{11}
10	10	
12	12 C	$\mathbb{Z}_{12}, \mathbb{Z}_2 \times \mathbb{Z}_6, A_4, D_6, T$
	0	$D_1(12, \mathbb{Z}_6), D_1(12, D_3)$ $D_1(12, \mathbb{Z}_6), D_1(12, \mathbb{Z}_6), D_1(12$
	4	$D_1(12, \mathbb{Z}_4), D_1(12, \mathbb{Z}_2 \times \mathbb{Z}_2), D_2(12, \mathbb{Z}_4), D_2(12, \mathbb{Z}_2 \times \mathbb{Z}_2)$ $D_1(12, \mathbb{Z}_4), D_2(12, \mathbb{Z}_2 \times \mathbb{Z}_2)$
	ა ი	$D_1(12, \mathbb{Z}_3), D_2(12, \mathbb{Z}_3)$ $D_1(12, \mathbb{Z}_3), D_2(12, \mathbb{Z}_3), D_1(12, \mathbb{Z}_3)$
	∠ 1	$D_1(12, \mathbb{Z}_2), D_2(12, \mathbb{Z}_2), D_3(12, \mathbb{Z}_2)$
12	12	7
10	10	∠213 trivial
1/	1/	\mathbb{Z}_{+} D-
14	$\frac{14}{7}$	$\mathbb{Z}_{14}, \mathbb{D}_7$ $\mathbb{D}_1(14, \mathbb{Z}_2)$
	1	$D_1(14, \mathbb{Z}_7)$ $D_2(14, \mathbb{Z}_7)$ $D_2(14, \mathbb{Z}_7)$ $D_2(14, \mathbb{Z}_7)$ $D_2(14, \mathbb{Z}_7)$
	ے 1	$D_1(14, \mathbb{Z}_2), D_2(14, \mathbb{Z}_2), D_3(14, \mathbb{Z}_2), D_4(14, \mathbb{Z}_2)$
15	15	
10	5	D_{10} $D_{1}(15 \ \mathbb{Z}_{r})$
	3	$D_1(15, \mathbb{Z}_2)$ $D_2(15, \mathbb{Z}_2)$
	1	$L_{1}(10, \omega_{3}), L_{2}(10, \omega_{3})$
	-	v11,1001

6. The classification of $D_i(n, J)$

There are some digroups, however, which do not qualify as Principal Digroups because the partitioning of the \dashv Cayley table for those digroups do not correspond to the \vdash partitions. However, since every structural property of the \vdash Cayley table holds for the \dashv Cayley table and since the inverse sets for the two tables must be isomorphic, the entire \dashv Cayley table is uniquely determined by how the digroup partitions into its inverse sets for all of its identities. Therefore, determining which permutations of the partitions of \dashv yield distinct digroup structures completes the classification of $D_i(n,J)$ for all i.

Lemma 6.1. Consider an arbitrary digroup (G, \vdash, \dashv) , with. Let \sim indicate the grouping of two elements within the same \dashv partition. Notice that \sim is an equivalence relation. If $x, c \in G$ and $x \sim c$, then $(x \vdash x) \sim (x \vdash c)$.

Proof. Assume $x \sim c$. Then, there exists some $z \in G$ such that $x \dashv z = c$. So, $x \vdash (x \dashv z) = x \vdash c$ also, $(x \vdash x) \dashv z = x \dashv c$. Thus, by $G2^*$, $(x \vdash x) \sim (x \vdash c)$. \Box

Lemma 6.2. If |J| = p, and $a_i \vdash e \sim e$ then the partition is equal to the set of inverses J.

Proof. Let $a_i \vdash e \sim e$. $a_i \vdash e \sim e \Rightarrow a_i^2 \vdash e \sim a_i \vdash e$ or $a_i^2 \vdash e \sim e$. Therefore by induction, assume $a_i^k \vdash e \sim e$. $a \vdash e \sim a_i^k \vdash e \Rightarrow a_i^2 \vdash e \sim a_i^{k+1} \vdash e$. Therefore $a_i^{k+1} \sim e$.

Theorem 6.3. Consider a digroup (G, \vdash, \dashv) with |G| = n. The number of digroups with $|E| = \frac{n}{n}$ is exactly

$$\left\lfloor \frac{\frac{n}{p} - 1}{p} \right\rfloor + 1$$

Proof. Consider the digroup axiom $x \vdash (x \dashv z) = (x \vdash x) \dashv z$. Let $J = \mathbb{Z}_p$. Consider $a_i \vdash e_{j_1} \sim e_2$. $a_i \vdash e_{j_1} \sim e_{j_2} \Rightarrow (a_i \vdash a_i) \vdash e_{j_1} \sim a_i \vdash e_{j_2} \sim (a_i \circ a_i) \vdash e_{j_1} \sim a_i^2 \vdash e_{j_1}$, where \circ indicates the binary operation of \mathbb{Z}_p .

We know that each partition should have order p therefore these two elements must be with another element, one of which must be an identity. By Lemma 6.2 we know that it cannot be either e_{j_1} or e_{j_2} , therefore it must be e_{j_3} . Therefore, $a_i^2 \vdash e_{j_1} \sim a_i \vdash e_{j_2} \Rightarrow a_i^4 \vdash e_{j_1} \sim a_i^3 \vdash e_{j_2}$, and $a_i \vdash e_{j_2} \sim e_{j_3} \Rightarrow a_i^2 \vdash e_{j_2} \sim a_i \vdash e_{j_3}$. Creating a table the pattern becomes apparent.

Partition						
1	$a_i \vdash e_1$	e_2	$a_i^{p-1} \vdash e_3$	$a_i^{p-2} \vdash e_4$	• • •	$a_i^2 \vdash e_p$
2	$a_i^2 \vdash e_1$	$a_i \vdash e_2$	e_3	$a_i^{p-1} \vdash e_4$	•••	$a_i^3 \vdash e_p$
3	$a_i^3 \vdash e_1$	$a_i^2 \vdash e_2$	$a_i \vdash e_3$	e_4	•••	$a_i^4 \vdash e_p$
4	$a_i^4 \vdash e_1$	$a_i^3 \vdash e_2$	$a_i^2 \vdash e_3$	$a_i \vdash e_4$	•••	$a_i^5 \vdash e_p$
÷	•	:	:	•	۰.	÷
р	e_1	$a_i^{p-1} \vdash e_2$	$a_i^{p-2} \vdash e_3$	$a_i^{p-3} \vdash e_4$	•••	$a_i \vdash e_p$

Therefore every partition is linked p ways, and a permutation in the partitions would have to have order p. This means the total number of permutations available will correspond to the number of partitions, $\frac{n}{p}$, minus 1 for the partition containing the bar unit, divided by p for the p-wise linking:

$$|\mathbf{D}_i(\mathbf{G})| = \left\lfloor \frac{\frac{n}{p} - 1}{p} \right\rfloor + 1$$
, where $|\mathbf{J}| = p$

It is clear that it does not matter which p partitions are changed as long as p are changed. Consider the previous table only with $\bar{a}_i \vdash \bar{e}_j$, the grouping of p different partitions together. Simply permute, or relabling these all of the elements in this table by $(\bar{a}_i \ a_i)(\bar{e}_j \ e_j)$, this gives the first table, therefore the digroup structures are isomorphic. Since we are only considering non-isomorphic structures we only consider the first.

Note that Corollary 1.5 on digroups of prime order follows trivially from Theorem 6.3. It is natural to consider digroups of order p^2 and $p \cdot q$ where p, q prime:

Corollary 6.4. There are only four digroups of order p^2 : the trivial digroup, $D_1(p^2, \mathbb{Z}_p)$, and the groups \mathbb{Z}_{p^2} and $\mathbb{Z}_p \times \mathbb{Z}_p$.

Proof. Let G be a digroup of order p^2 and E its identity set. The only possible decompositions of p^2 are $p^2 \cdot 1$, $p \cdot p$, and $1 \cdot p^2$. Therefore, we only have to consider the cases where |E| = 1, p, or p^2 .

(1) If |E| = 1, then the digroup is a group and it is known that it must be either \mathbb{Z}_{p^2} or $\mathbb{Z}_p \times \mathbb{Z}_p$.

(2) If |E| = p, then Theorem 6.3 tells us there is only \$\begin{bmatrix} \frac{p^2}{p} - 1 \\ \frac{p}{p} \end{bmatrix} + 1 = \$\begin{bmatrix} \frac{p-1}{p} \end{bmatrix} + 1 = \$1\$ digroup of order \$p^2\$. We label this digroup \$D_1(p^2, \matrix_p)\$.
(3) If |E| = \$p^2\$, then the digroup is trivial.

Corollary 6.5. Let G be a digroup. If $|G| = p \cdot q$ where p, q prime and p > q, then there are only $\left|\frac{q-1}{p}\right| + 2$ non-trivial non-group possibilities for G.

Proof. Let G be a digroup of order $p \cdot q$ and E its identity set. Let p > q without loss of generality. The only possible decompositions of $p \cdot q$ are $(p \cdot q) \cdot 1$, $p \cdot q$, $q \cdot p$, and $1 \cdot (p \cdot q)$. Therefore, we only have to consider the cases where |E| = 1, p, q, or $p \cdot q$.

- (1) If |E| = 1, G is a group.
- (2) If |E| = p, then Theorem 6.3 tells us there are only $\left\lfloor \frac{p \cdot q}{q} 1 \atop q \right\rfloor + 1 = \left\lfloor \frac{p-1}{q} \right\rfloor + 1 = 1$ digroups of order $p \cdot q$. In this case, $G = D_1(p \cdot q, \mathbb{Z}_q)$.
- (3) If |E| = q, then Theorem 6.3 tells us there is only $\left\lfloor \frac{p \cdot q}{p} \right\rfloor + 1 = \left\lfloor \frac{q-1}{p} \right\rfloor + 1$ digroups of order $p \cdot q$.
- (4) If $|E| = p \cdot q$, G is trivial.

 \square

7. CONCLUSION

While an analogue of Lie's Third Theorem for Leibniz Algebra has yet to be found it has been conjectured by some that the answer still lies within the structure of digroups. Our hopes is that a more detailed structural analysis of digroups can help to point out possibilities for finding that answer.

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